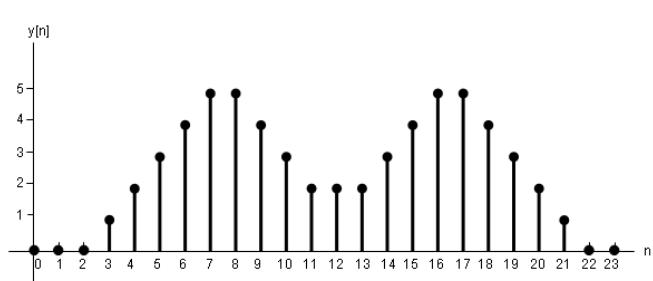


SISTEMAS LINEALES

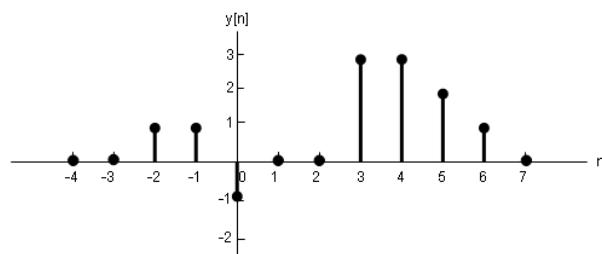
TEMA 2. SOLUCIONES NUMÉRICAS DE LA HOJA DE PROBLEMAS

1. (a) $y_1[n] = x[n] * h[n] = 2\delta[n+1] + 4\delta[n] + 2\delta[n-1] + 2\delta[n-2] - 2\delta[n-4]$
 (b) $y_2[n] = x[n+2]*h[n] = y_1[n+2] = 2\delta[n+3]+4\delta[n+2]+2\delta[n+1]+2\delta[n]-2\delta[n-2]$
 (c) $y_3[n] = x[n]*h[n+2] = y_1[n+2] = 2\delta[n+3]+4\delta[n+2]+2\delta[n+1]+2\delta[n]-2\delta[n-2]$
2. $A = n - 9, B = n + 3.$
3. (a) $x[n] = \alpha^n u[n],$
 $h[n] = \beta^n u[n], \alpha \neq \beta$
 $y[n] = \frac{\beta^{n+1} - \alpha^{n+1}}{\beta - \alpha} u[n]$
- (b) $x[n] = h[n] = \alpha^n u[n]$
 $y[n] = \alpha^n (n+1) u[n]$
- (c) $x[n] = 2^n u[-n]$
 $h[n] = u[n]$
 $y[n] = \begin{cases} 2^{n+1}, & n < 0 \\ 2, & n \geq 0 \end{cases}$
- (d) $x[n] = (-1)^n (u[-n] - u[-n-8])$
 $h[n] = u[n] - u[n-8]$
 $y[n] = \begin{cases} 0, & n < -7 \\ \begin{cases} -1, & n \text{ impar} \\ 0, & n \text{ par} \end{cases}, & -7 \leq n < 0 \\ \begin{cases} 1, & n \text{ impar} \\ 0, & n \text{ par} \end{cases}, & 0 \leq n \leq 7 \\ 0, & n > 7 \end{cases}$

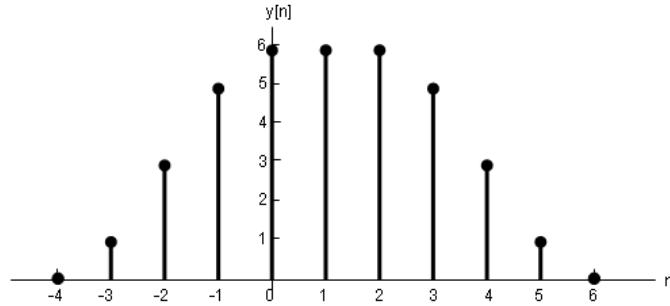
(e) $y[n]$



(f) $y[n]$



(g) $y[n]$



(h) $x[n] = 1$ para todo n , $h[n] = \begin{cases} \left(\frac{1}{2}\right)^n, & n \geq 0 \\ 4^n, & n < 0 \end{cases}$
 $y[n] = \frac{7}{3}$ para todo n .

(i) $x[n] = u[n] - u[-n]$ para todo n , $h[n] = \begin{cases} \left(\frac{1}{2}\right)^n, & n \geq 0 \\ 4^n, & n < 0 \end{cases}$

$$y[n] = \left[\frac{7}{3} - 3\left(\frac{1}{2}\right)^n\right]u[n] + \left[\frac{5}{3}4^n - \frac{7}{3}\right]u[-n-1]$$

(j) $x[n] = \left(\frac{1}{2}\right)^n u[n]$
 $h[n] = 4^n u[2-n]$
 $y[n] = \begin{cases} \frac{1}{2}2^{2n+3}, & n < 2 \\ \frac{1}{7}2^{9-n}, & n \geq 0 \end{cases}$

(k) (Examen Feb. 2007, ejercicio 2)

$$x[n] = \alpha^n(u[n] - u[n-10]), \quad 0 < \alpha < 1$$

$$y[n] = \beta^n u[n+5], \quad 0 < \beta < 1$$

$$y[n] = \begin{cases} 0, & n < -5 \\ \frac{\beta^{n+6} - \alpha^{n+6}}{\beta^5(\beta - \alpha)}, & -5 \leq n \leq 4 \\ \frac{\beta^{n+1} - \beta^{n-9}\alpha^{10}}{\beta - \alpha}, & n > 4 \end{cases}$$

4. (a) $x(t) = e^{-\alpha t}u(t)$

$$h(t) = e^{-\beta t}u(t) \text{ (Haga este ejercicio para } \alpha \neq \beta \text{ y para } \alpha = \beta).$$

$$y(t) = \frac{e^{-\alpha t} - e^{-\beta t}}{\beta - \alpha}u(t), \text{ si } \alpha \neq \beta.$$

$$y(t) = te^{-\alpha t}u(t), \text{ si } \alpha = \beta.$$

(b) $x(t) = u(t) - 2u(t-2) + u(t-5)$

$$h(t) = e^{2t}u(1-t)$$

$$y(t) = \begin{cases} \frac{1}{2}(e^{2t} - 2e^{2(t-2)} + e^{2(t-5)}), & t \leq 1 \\ \frac{1}{2}(e^2 - 2e^{2(t-2)} + e^{2(t-5)}), & 1 \leq t \leq 3 \\ \frac{1}{2}(e^{2(t-5)} - e^2), & 3 \leq t \leq 6 \\ 0, & t \geq 6 \end{cases}$$

o bien:

$$y(t) = \frac{1}{2}[e^{2t} - e^2]u(1-t) + [e^2 - e^{2(t-2)}]u(3-t) + \frac{1}{2}[-e^2 + e^{2(t-5)}]u(6-t)$$

(c) $x(t) = e^{-3t}u(t)$

$$h(t) = u(t-1)$$

$$y(t) = \frac{1}{3}(1 - e^{-3(t-1)})u(t-1)$$

(d) $x(t) = e^{-2t}u(t+2) + e^{3t}u(-t+2)$
 $h(t) = e^t u(t-1)$
 $y(t) = \begin{cases} \frac{1}{2}e^{(3t-2)}, & t \leq -1 \\ \frac{1}{2}e^{(3t-2)} - \frac{1}{3}e^{(-2t+3)} + \frac{1}{3}e^{(t+6)}, & -1 \leq t \leq 3 \\ \frac{1}{2}e^{(t+4)} - \frac{1}{3}e^{(-2t+3)} + \frac{1}{3}e^{(t+6)}, & t \geq 3 \end{cases}$

o bien:

$$y(t) = \left[\frac{1}{2}e^{(3t-2)} - \frac{1}{3}e^{(-2t+3)} + \frac{1}{3}e^{(t+6)} \right] + \frac{1}{3} \left[e^{(-2t+3)} - e^{(t+6)} \right] u(-1-t) + \frac{1}{2} \left[e^{(t+4)} - e^{(3t-2)} \right] u(t-3)$$

(e) $x(t) = \begin{cases} e^t, & t < 0 \\ e^{5t} - 2e^{-t}, & t > 0 \end{cases}$

$h(t)$ como se muestra en la figura.

$$y(t) = \begin{cases} e^t - e^{(t-1)}, & t < 0 \\ \frac{1}{5}e^{5t} - e^{(t-1)} + 2e^{-t} - \frac{6}{5}, & 0 \leq t < 1 \\ \frac{1}{5} [e^{5t} - e^{5(t-1)}] + 2 [e^{-t} - e^{-(t-1)}], & t \geq 1 \end{cases}$$

o bien:

$$y(t) = \left[e^t - e^{(t-1)} \right] + \left[\frac{1}{5}e^{5t} - e^t + 2e^{-t} - \frac{6}{5} \right] u(t) + \left[-\frac{1}{5}e^{5(t-1)} + e^{(t-1)} - 2e^{-(t-1)} + \frac{6}{5} \right] u(t-1)$$

(f) $x(t)$ y $h(t)$ como se muestran en la figura.

$$y(t) = \begin{cases} 0, & t \leq 1 \\ \frac{1}{\pi} [1 + \cos(\pi t)], & 1 < t \leq 3 \\ -\frac{1}{\pi} [1 + \cos(\pi t)], & 3 < t \leq 5 \\ 0, & t > 5 \end{cases}$$

o bien:

$$y(t) = \frac{1}{\pi} [1 + \cos(\pi t)] u(t-1) - \frac{2}{\pi} [1 + \cos(\pi t)] u(t-3) + \frac{1}{\pi} [1 + \cos(\pi t)] u(t-5)$$

(g) $x(t)$ como se muestra en la figura, y $h(t) = u(-2-t)$.

$$y(t) = \begin{cases} 7, & t \leq -1 \\ 4 - 3t, & -1 < t \leq 0 \\ 4 - t, & 0 < t \leq 4 \\ 0, & t > 4 \end{cases}$$

o bien:

$$y(t) = 7 - 3(t+1)u(t+1) + 2tu(t) + (t-4)u(t-4)$$

(h) $x(t) = \delta(t) - 2\delta(t-1) + \delta(t-2)$, y $h(t)$ como se muestra en la figura.

$$y(t) = \begin{cases} 0, & t < 0 \\ 1, & 0 < t < 1 \\ 0, & 1 < t < 2 \\ -3, & 2 < t < 3 \\ 2, & 3 < t < 4 \\ 0, & t > 4 \end{cases}$$

(i) $x(t)$ y $h(t)$ como se muestran en la figura.

$$y(t) = at + b$$

(j) $x(t)$ y $h(t)$ como se muestran en la figura.

$$y(t) = \frac{dx(t)}{dt} = \begin{cases} 0, & t < -1 \\ 1, & -1 < t < 0 \\ -1, & 0 < t < 1 \\ 0, & t > 1 \end{cases}$$

(k) $x(t)$ y $h(t)$ como se muestran en la figura.

$y(t)$ es periódico con periodo $T_0 = 2$, por serlo $x(t)$, siendo en un periodo:

$$y(t) = \begin{cases} -t^2 + t + \frac{1}{4}, & -\frac{1}{2} < t \leq \frac{1}{2} \\ t^2 - 3t + \frac{7}{4}, & \frac{1}{2} < t \leq \frac{3}{2} \end{cases}$$

(l) $x(t)$ como se muestra en la figura, y $h(t) = e^{-t} [u(t-1) - u(t-2)]$.

$$y(t) = \begin{cases} 0, & t < 1 \\ (t-2)e^{-1} + e^{-t}, & 1 \leq t < 2 \\ (3-t)e^{-2} + e^{-1} - e^{(1-t)}, & 2 \leq t < 3 \\ e^{(2-t)} - e^{-2}, & 3 \leq t < 4 \\ 0, & t \geq 4 \end{cases}$$

o bien:

$$y(t) = [(t-2)e^{-1} + e^{-t}] u(t-1) + [(3-t)(e^{-1} + e^{-2}) - (1+e)e^{-t}] u(t-2) + [-e^{-1} + (t-4)e^{-2} + (e+e^2)e^{-t}] u(t-3) + [e^{-2} - e^{(2-t)}] u(t-4)$$

(m) $x(t)$ y $h(t)$ como se muestran en la figura.

$$y(t) = \begin{cases} 0, & t < -1 \\ \frac{1}{2}t^2 - \frac{1}{2}, & -1 \leq t < 0 \\ -\frac{1}{6}t^3 + t^2 - \frac{1}{2}, & 0 \leq t < 1 \\ -\frac{1}{2}t^2 + \frac{5}{2}t - \frac{5}{3}, & 1 \leq t < 2 \\ \frac{1}{6}t^3 - \frac{3}{2}t^2 + \frac{7}{2}t - 1, & 2 \leq t < 3 \\ \frac{1}{2}t^2 - 4t + 8, & 3 \leq t < 4 \\ 0, & t \geq 4 \end{cases}$$

o bien:

$$y(t) = \left[\frac{1}{2}t^2 - \frac{1}{2} \right] u(t+1) + \left[-\frac{1}{6}t^3 + \frac{1}{2}t^2 \right] u(t) + \left[\frac{1}{6}t^3 - \frac{3}{2}t^2 + \frac{5}{2}t - \frac{7}{6} \right] u(t-1) + \left[\frac{1}{6}t^3 - t^2 + t + \frac{2}{3} \right] u(t-2) + \left[-\frac{1}{6}t^3 + 2t^2 - \frac{15}{2}t + 9 \right] u(t-3) + \left[-\frac{1}{2}t^2 + 4t - 8 \right] u(t-4)$$

(n) (Examen Sept. 2008, ejercicio 1)

$$x(t) = e^{-2t} [u(t-1) - u(t-4)],$$

$$h(t) = e^{2t} [u(1-t) - u(-1-t)].$$

$$y(t) = \begin{cases} 0, & t < 0 \\ \frac{1}{4} (e^{(2t-4)} - e^{-(2t+4)}), & 0 \leq t < 2 \\ \frac{1}{4} (e^{(-2t+4)} - e^{-(2t+4)}), & 2 \leq t < 3 \\ \frac{1}{4} (e^{(-2t+4)} - e^{(2t-16)}), & 3 \leq t < 5 \\ 0, & t \geq 5. \end{cases}$$

(o) (Examen Feb. 2008, ejercicio 2)

$$h(t) \text{ como en la figura, y } x(t) = \sin(\pi t) [u(t+1) - u(t-1)].$$

$$y(t) = 0.$$

5. (Examen Feb. 2004, ejercicio 3)

Definiendo:

$$a(t) = \begin{cases} 1, & 0 \leq t < 1/2 \\ 0, & \text{resto,} \end{cases}$$

y

$$b(t) = a(t) * a(t) = \begin{cases} t, & 0 \leq t < 1/2 \\ 1-t, & 1/2 \leq t \leq 1 \\ 0, & \text{resto.} \end{cases}$$

- (a) $z_0(t) = b(t+4) + b(t+3) + b(t+2) - b(t) - b(t-1) - b(t-2)$.
 (b) $z_1(t) = z_0(t+1) = b(t+5) + b(t+4) + b(t+3) - b(t+1) - b(t) - b(t-1)$.
 (c) $z_2(t) = -b(t+7/2) - b(t+5/2) - b(t+3/2) + b(t-1/2) + b(t-3/2) + b(t-5/2)$.
 (d) $z_3(t) = \frac{dz_0(t)}{dt} = a(t+4) - a(t+7/2) + a(t+3) - a(t+5/2) + a(t+2) - a(t+3/2) - a(t) + a(t-1/2) - a(t-1) + a(t-3/2) - a(t-2) + a(t-5/2)$.

6. (a) $h(t) = e^{-(t-2)}u(t-2)$

(b) $y(t) = \begin{cases} 0, & t < 1 \\ 1 - e^{-(t-1)}, & 1 \leq t < 4 \\ e^{-(t-4)} - e^{-(t-1)} = (1 - e^{-3})e^{-(t-4)}, & t \geq 4 \end{cases}$

o bien:

$$y(t) = [1 - e^{-(t-1)}] u(t-1) + [e^{-(t-4)} - 1] u(t-4)$$

(c) $h_2(t) = e^{-(t-2)}u(t-2) - e^{-(t-3)}u(t-3)$

$$y_2(t) = y(t) - y(t-1) = [1 - e^{-(t-1)}] u(t-1) - [1 - e^{-(t-2)}] u(t-2) + [e^{-(t-4)} - 1] u(t-4) - [e^{-(t-5)} - 1] u(t-5)$$

7. Si se convoluciona una señal con un tren de impulsos, a la salida tenemos un tren de versiones desplazadas de la señal.

(a) $y(t) = \sum_{k=-\infty}^{\infty} h(t-kT)$

(b) $y(t) = \sum_{k=-\infty}^{\infty} e^{-(t-k)}u(t-k)$

$y(t)$ es una señal periódica de periodo $T_0 = 1$, siendo en el intervalo $0 < t < 1$:

$$y(t) = \frac{e^{(1-t)}}{e-1}, \quad 0 < t < 1.$$

(c) $y(t) = \sum_{k=-\infty}^{\infty} (-1)^k h(t-k) = \sum_{k=-\infty}^{\infty} (-1)^k [u(t-k) - u(t-k-1)] = \dots + 2u(t+2) - 2u(t+1) + 2u(t) - 2u(t-1) + 2u(t-2) + \dots$

8. Calcule y dibuje $y[n] = x[n] * h[n]$.

$$y[n] = \begin{cases} 0, & n < 7 \\ n-6, & 7 \leq n \leq 11 \\ 6, & 12 \leq n \leq 18 \\ 24-n, & 19 \leq n \leq 23 \\ 0, & n \geq 24 \end{cases}$$

9. (a) $y(t) = \frac{1}{3} [1 - e^{-3(t-3)}] u(t-3) + \frac{1}{3} [e^{-3(t-5)} - 1] u(t-5)$

o bien:

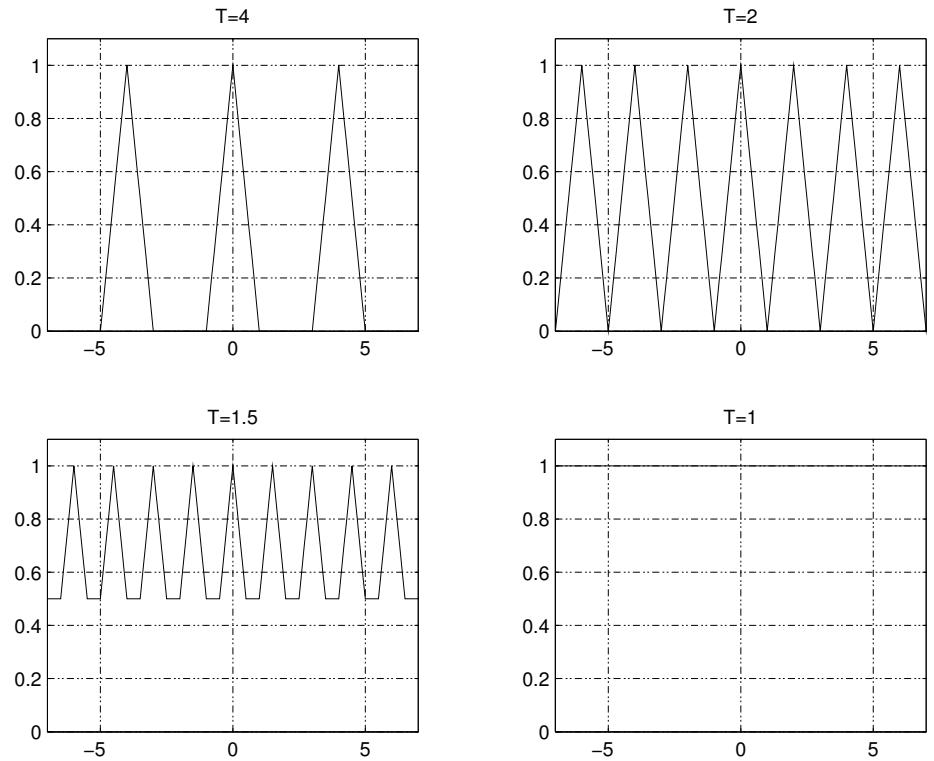
$$y(t) = \begin{cases} 0, & t < 3 \\ \frac{1}{3} [1 - e^{-3(t-3)}], & 3 \leq t < 5 \\ \frac{1}{3} e^{-3(t-5)} [1 - e^{-6}], & t \geq 5 \end{cases}$$

(b) $g(t) = e^{-3(t-3)}u(t-3) - e^{-3(t-5)}u(t-5)$

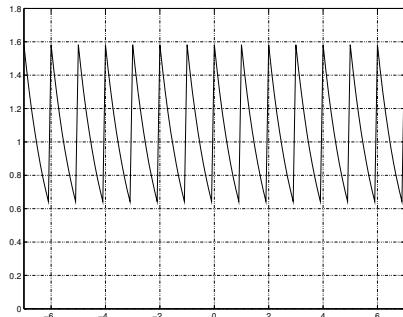
o bien:

$$g(t) = \begin{cases} 0, & t < 3 \\ e^{-3(t-3)}, & 3 \leq t < 5 \\ e^{-3(t-5)} [e^{-6} - 1], & t \geq 5 \end{cases}$$

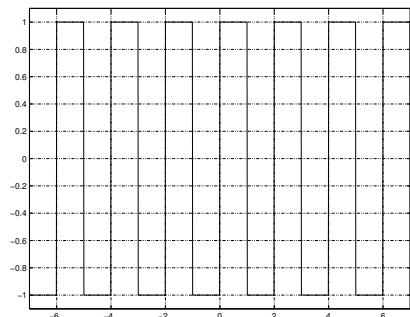
(c) $g(t) = \frac{dy(t)}{dt}$



(a)



(b)



(c)

Figure 1: Resultados gráficos del problema 6.

10. (a) Estable.

(b) Estable.

11. $y[n] = \left(\frac{1}{4}\right)^{(n-1)} u[n-1]$

12. (Examen Sept. 2007, ejercicio 1)

(a) $y(t) = \frac{\sin(3\pi t)}{2(1+9\pi^2)} - 3\pi \frac{\cos(3\pi t)}{2(1+9\pi^2)} - \frac{\sin(\pi t)}{2(1+\pi^2)} + \pi \frac{\cos(\pi t)}{2(1+\pi^2)}.$

(b) Con memoria, no causal, no invertible y no estable.

13. (Examen Feb. 2005, ejercicio 1)

(a) Con memoria, causal y no estable.

(b) Problema 4d.

14. Sistema no estable. (Examen Sept. 2004, ejercicio 3b)

15. Falso (tema 4). (Examen Sept. 2004, ejercicio 3d)

16. (a)

$$\begin{aligned}
 y(t) &= x(t) * h(t) = \left[\sum_{l=-\infty}^{\infty} x_l \delta(t - lT) \right] * h(t) = \sum_{l=-\infty}^{\infty} x_l h(t - lT) \\
 &= \sum_{l=-\infty}^{\infty} x_l \sum_{m=-\infty}^{\infty} h_m \delta(t - (l+m)T) = (\text{c.v. } n=l+m) \\
 &= \sum_{l=-\infty}^{\infty} x_l \sum_{n=-\infty}^{\infty} h_{n-l} \delta(t - nT) = \sum_{n=-\infty}^{\infty} \sum_{l=-\infty}^{\infty} x_l h_{n-l} \delta(t - nT) \\
 &= \sum_{n=-\infty}^{\infty} \delta(t - nT) \left(\sum_{l=-\infty}^{\infty} x_l h_{n-l} \right) = \sum_{n=-\infty}^{\infty} y_n \delta(t - nT),
 \end{aligned}$$

donde $\{y_n\} = \{x_n\} * \{h_n\} = \sum_{n=-\infty}^{\infty} x_k h_{n-k}$, como queríamos demostrar.

(b) $h(t) = \delta(t) - \delta(t - T)$

(d) $h_1(t) = \sum_{n=-\infty}^{\infty} h_n \delta(t - nT)$,

$h_2(t) = u(t) - u(t - 1)$,

$$\begin{aligned}
 h(t) &= h_1(t) * h_2(t) = h_2(t) * h_1(t) = [u(t) - u(t - 1)] * \sum_{n=-\infty}^{\infty} h_n \delta(t - nT) \\
 &= \sum_{n=-\infty}^{\infty} h_n [h_2(t) * \delta(t - nT)] = \sum_{n=-\infty}^{\infty} h_n h_2(t - nT), \quad \text{c.q.d.}
 \end{aligned}$$

17. $\phi_{xy}(t) = x(t) * y(-t)$.

$\phi_{xx}(t) = x(t) * x(-t)$, es siempre una función par. Se puede calcular mediante esta relación, o directamente, y es útil tener en cuenta que es par.

$$\text{(a)} \quad \phi_{x_1 x_1}(t) = \begin{cases} 0, & t \leq -2 \\ \frac{1}{24} (-t^3 + 12t + 16), & -2 < t \leq 0 \\ \frac{1}{24} (t^3 - 12t + 16), & 0 < t \leq 2 \\ 0, & t > 2 \end{cases}$$

o bien:

$$\phi_{x_1x_1}(t) = \begin{cases} \frac{1}{24}(|t|^3 - 12|t| + 16), & |t| \leq 2 \\ 0, & |t| > 2 \end{cases}$$

$$\phi_{x_2x_2}(t) = \begin{cases} -7|t| + 7, & |t| \leq 1 \\ -|t| + 1, & 1 < |t| \leq 2 \\ |t| - 3, & 2 < |t| \leq 3 \\ -|t| + 3, & 3 < |t| \leq 4 \\ |t| - 5, & 4 < |t| \leq 5 \\ 5 - |t|, & 5 < |t| \leq 6 \\ |t| - 7, & 6 < |t| \leq 7 \\ 0, & |t| > 7 \end{cases}$$

(b) $h(t) = x(T - t)$. Filtro adaptado (o de acoplamiento) para $x(t)$.

18. Problemas de ampliación:

2.5. $N = 4$

$$2.6. \quad y[n] = \begin{cases} \frac{1}{2}3^n, & n \leq 0 \\ \frac{1}{2}, & n > 0 \end{cases}$$

$$2.7. \quad (a) \quad y[n] = g[n - 2] = u[n - 2] - u[n - 6]$$

$$(b) \quad y[n] = g[n - 4] = u[n - 4] - u[n - 8]$$

(c) No es invariante con respecto al tiempo, con lo que no es LTI.

$$(d) \quad y[n] = \sum_{k=0}^{\infty} g[n - 2k].$$

Obteniendo $y[n]$ para $k = 0, 1, 2, \dots$, y por inducción:

$$y[n] = \begin{cases} 0, & n < 0 \\ 1, & n = 0, 1 \\ 2, & n \geq 2 \end{cases}$$

$$2.8. \quad y(t) = \begin{cases} 0, & t \leq -2 \\ t + 3, & -2 < t \leq -1 \\ t + 4, & -1 < t \leq 0 \\ 2 - 2t, & 0 < t \leq 1 \\ 0, & t > 1 \end{cases}$$

2.15. (a) Inestable; (b) Estable.

$$2.24. \quad (a) \quad h_1[n] = \delta[n] + 3\delta[n - 1] + 3\delta[n - 2] + 2\delta[n - 3] + \delta[n - 4]$$

$$(b) \quad y[n] = \begin{aligned} &\delta[n] + 4\delta[n - 1] + 5\delta[n - 2] + \delta[n - 3] - 3\delta[n - 4] - 4\delta[n - 5] \\ &- 3\delta[n - 6] - \delta[n - 7] \end{aligned}$$

2.28. (a) Causal y estable.

(b) No causal y estable.

(c) No causal y no estable.

(d) No causal y estable.

(e) Causal y no estable.

(f) No causal y estable.

(g) Causal y estable.

$$2.33. \quad (a) \quad (i) \quad y_1(t) = \frac{1}{5} [e^{3t} - e^{-2t}] u(t)$$

$$(ii) \quad y_2(t) = \frac{1}{4} [e^{2t} - e^{-2t}] u(t)$$

$$(iii) \quad y_3(t) = \frac{1}{5}\alpha [e^{3t} - e^{-2t}] u(t) + \frac{1}{4}\beta [e^{2t} - e^{-2t}] u(t) = \alpha y_1(t) + \beta y_2(t), \quad \text{c.q.d.}$$

(iv) $x_1(t)$ e $y_1(t)$ cumplen la ecuación diferencial:

$$\frac{dy_1(t)}{dt} + 2y_1(t) = x_1(t), \quad y_1(t) = 0, t < t_1;$$

asimismo, $x_2(t)$ e $y_2(t)$ también cumplen la ecuación diferencial:

$$\frac{dy_2(t)}{dt} + 2y_2(t) = x_2(t), \quad y_2(t) = 0, t < t_2.$$

Multiplicando la primera ecuación por α y la segunda por β y sumándolas, se llega a la siguiente ecuación diferencial:

$$\begin{aligned} \frac{d}{dt} \{ \alpha y_1(t) + \beta y_2(t) \} + 2 \{ \alpha y_1(t) + \beta y_2(t) \} &= \alpha x_1(t) + \beta x_2(t), \\ \alpha y_1(t) + \beta y_2(t) &= 0, t < \min\{t_1, t_2\}. \end{aligned}$$

Por inspección se ve claramente que la salida es $y_3(t) = \alpha y_1(t) + \beta y_2(t)$, cuando la entrada es $x_3(t) = \alpha x_1(t) + \beta x_2(t)$.

El sistema es lineal, c.q.d.

- (b) (i) $y_1(t) = \frac{K}{4} [e^{2t} - e^{-2t}] u(t)$
- (ii) $y_2(t) = \frac{K}{4} [e^{2(t-T)t} - e^{-2(t-T)t}] u(t-T) = y_1(t-T)$, c.q.d.
- (iii) $x_1(t)$ e $y_1(t)$ cumplen la ecuación diferencial:

$$\frac{dy_1(t)}{dt} + 2y_1(t) = x_1(t), \quad y_1(t) = 0, t < t_0;$$

como la derivada posee la propiedad de invarianza temporal, se puede escribir:

$$\begin{aligned} \frac{dy_1(t-T)}{dt} + 2y_1(t-T) &= x_1(t-T), \quad y_1(t) = 0, t < t_0 \\ , \text{ o bien } y_1(t-T) &= 0, t < t_0 + T. \end{aligned}$$

Por inspección se puede ver fácilmente que cuando la entrada es $x_2(t) = x_1(t-T)$, la salida es $y_2(t) = y_1(t-T)$.

Además, $y_2(t) = 0, t < t_0 + T$, lo cual es lógico pues $x_2(t) = x_1(t-T) = 0, t < t_0 + T$.

El sistema es invariante en el tiempo, c.q.d.

- 2.38. (a) Ver figura ??.
- (b) Ver figura ??.
- 2.39. (a) Ver figura ??.
- (b) Ver figura ??.

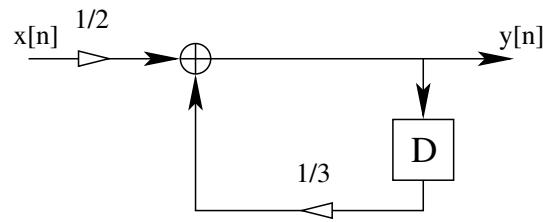


Figure 2: Ejercicio 2.38 (a).

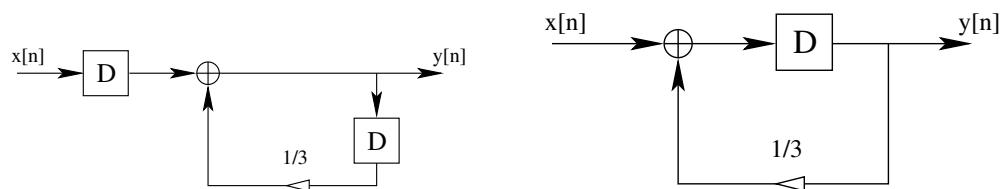


Figure 3: Ejercicio 2.38 (b).

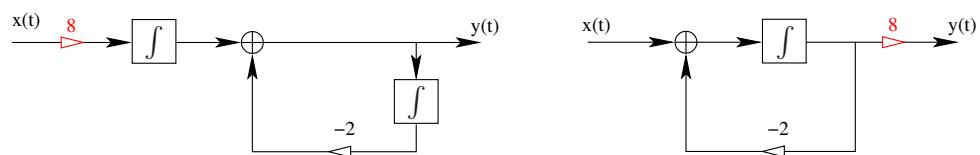


Figure 4: Ejercicio 2.39 (a).

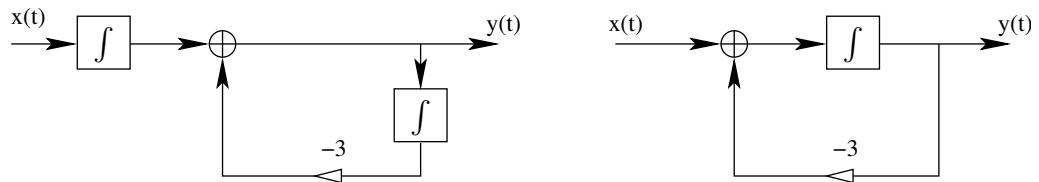


Figure 5: Ejercicio 2.39 (b).